

On P -Sasakian Manifolds Satisfying Certain Conditions on the Conircular Curvature Tensor

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Abstract

We classify P -Sasakian manifolds, which satisfy the conditions $Z(\xi, X) \cdot Z = 0$, $Z(\xi, X) \cdot R = 0$, $R(\xi, X) \cdot Z = 0$, $Z(\xi, X) \cdot S = 0$ and $Z(\xi, X) \cdot C = 0$.

Key Words: P -Sasakian manifold, concircular curvature tensor, Weyl conformal curvature tensor.

1. Introduction

A Riemannian manifold M is locally symmetric if its curvature tensor R satisfies $\nabla R = 0$, where ∇ is Levi-Civita connection of the Riemannian metric. As a generalization of locally symmetric spaces, many geometers have considered semi-symmetric spaces and in turn their generalizations. A Riemannian manifold M is said to be semi-symmetric if its curvature tensor R satisfies

$$R(X, Y) \cdot R = 0, \quad X, Y \in TM,$$

where $R(X, Y)$ acts on R as a derivation.

Locally symmetric and semisymmetric P -Sasakian manifolds are studied in [2] and [5]. After the curvature tensor, the Weyl conformal curvature tensor C and the concircular curvature tensor Z are the next most important tensors. In this paper, we study several derivation conditions on P -Sasakian manifolds. The paper is organized as follows. In

section 2, we give a brief account of P -Sasakian manifolds, the Weyl conformal curvature tensor and the concircular curvature tensor. In section 3, we find necessary and sufficient conditions for P -Sasakian manifolds satisfying the conditions like $Z(\xi, X) \cdot Z = 0$, $Z(\xi, X) \cdot R = 0$, $R(\xi, X) \cdot Z = 0$, $Z(\xi, X) \cdot S = 0$ and $Z(\xi, X) \cdot C = 0$. In Section 4, we prove that for an n -dimensional P -Sasakian manifold M the following three statements are equivalent: (a) M is locally symmetric, (b) M is concircularly symmetric and (c) M is locally isometric to the Hyperbolic space $H^n(-1)$.

2. P -Sasakian Manifolds

An n -dimensional differentiable manifold M is called an *almost paracontact manifold* if it admits an almost paracontact structure (φ, ξ, η) consisting of a $(1, 1)$ tensor field φ , a vector field ξ , and a 1-form η satisfying

$$\varphi^2 = Id - \eta \otimes \xi, \quad \eta(\xi) = 1, \quad \varphi\xi = 0, \quad \eta \circ \varphi = 0. \quad (2.1)$$

The first and one of the remaining three relations in (2.1) imply the other two relations in (2.1). Let g be a compatible Riemannian metric with (φ, ξ, η) , that is,

$$g(X, Y) = g(\varphi X, \varphi Y) + \eta(X)\eta(Y) \quad (2.2)$$

or equivalently,

$$g(X, \varphi Y) = g(\varphi X, Y) \quad \text{and} \quad g(X, \xi) = \eta(X) \quad (2.3)$$

for all $X, Y \in TM$. Then, M becomes an *almost paracontact Riemannian manifold* equipped with an almost paracontact Riemannian structure (φ, ξ, η, g) .

An almost paracontact Riemannian manifold is called a *P -Sasakian manifold* if it satisfies

$$(\nabla_X \varphi)Y = -g(X, Y)\xi - \eta(Y)X + 2\eta(X)\eta(Y)\xi, \quad X, Y \in TM, \quad (2.4)$$

where ∇ is Levi-Civita connection of the Riemannian metric. From the above equation it follows that

$$\nabla \xi = \varphi, \quad (2.5)$$

$$(\nabla_X \eta)Y = g(X, \varphi Y) = (\nabla_Y \eta)X, \quad X \in TM. \quad (2.6)$$

In an n -dimensional P -Sasakian manifold M , the curvature tensor R , the Ricci tensor S , and the Ricci operator Q satisfy

$$R(X, Y)\xi = \eta(X)Y - \eta(Y)X, \quad (2.7)$$

$$R(\xi, X)Y = \eta(Y)X - g(X, Y)\xi, \quad (2.8)$$

$$R(\xi, X)\xi = X - \eta(X)\xi, \quad (2.9)$$

$$S(X, \xi) = -(n-1)\eta(X), \quad (2.10)$$

$$Q\xi = -(n-1)\xi, \quad (2.11)$$

$$\eta(R(X, Y)U) = g(X, U)\eta(Y) - g(Y, U)\eta(X), \quad (2.12)$$

$$\eta(R(X, Y)\xi) = 0, \quad (2.13)$$

$$\eta(R(\xi, X)Y) = \eta(X)\eta(Y) - g(X, Y). \quad (2.14)$$

An almost paracontact Riemannian manifold M is said to be η -Einstein [2] if the Ricci operator Q satisfies

$$Q = aId + b\eta \otimes \xi, \quad (2.15)$$

where a and b are smooth functions on the manifold. In particular, if $b = 0$, then M is an Einstein manifold. For more details about almost paracontact Riemannian manifolds we refer to [2], [6] and [7].

Let (M, g) be an n -dimensional Riemannian manifold. Then the *concircular curvature tensor* Z and the *Weyl conformal curvature tensor* C are defined by [9]

$$Z(X, Y)U = R(X, Y)U - \frac{r}{n(n-1)}(g(Y, U)X - g(X, U)Y), \quad (2.16)$$

$$\begin{aligned} C(X, Y)U &= R(X, Y)U - \frac{1}{n-2}\{S(Y, U)X - S(X, U)Y \\ &\quad + g(Y, U)QX - g(X, U)QY\} \\ &\quad + \frac{r}{(n-1)(n-2)}\{g(Y, U)X - g(X, U)Y\} \end{aligned} \quad (2.17)$$

for all $X, Y, U \in TM$, respectively, where r is the scalar curvature of M .

3. Main Results

In this section, we obtain necessary and sufficient conditions for P -Sasakian manifolds satisfying the derivation conditions $Z(\xi, X) \cdot Z = 0$, $Z(\xi, X) \cdot R = 0$, $R(\xi, X) \cdot Z = 0$, $Z(\xi, X) \cdot S = 0$ and $Z(\xi, X) \cdot C = 0$.

Theorem 3.1 *An n -dimensional P -Sasakian manifold M satisfies*

$$Z(\xi, X) \cdot Z = 0$$

if and only if either the scalar curvature r of M is $r = n(1 - n)$ or M is locally isometric to the Hyperbolic space $H^n(-1)$.

Proof. In a P -Sasakian manifold M , we have

$$Z(X, Y)\xi = \left(1 - \frac{r}{n(n-1)}\right) (\eta(Y)X - \eta(X)Y), \quad (3.18)$$

$$Z(\xi, X)Y = \left(1 - \frac{r}{n(n-1)}\right) (g(X, Y)\xi - \eta(Y)X). \quad (3.19)$$

The condition $Z(\xi, U) \cdot Z = 0$ implies that

$$0 = [Z(\xi, U), Z(X, Y)]\xi - Z(Z(\xi, U)X, Y)\xi - Z(X, Z(\xi, U)Y)\xi,$$

which in view of (3.19) gives

$$\begin{aligned} 0 = & \left(1 + \frac{r}{n(n-1)}\right) \{-g(U, Z(X, Y)\xi) + g(U, X)Z(\xi, Y)\xi \\ & - \eta(X)Z(U, Y)\xi + g(U, Y)Z(X, \xi)\xi \\ & - \eta(Y)Z(X, U)\xi + \eta(U)Z(X, Y)\xi - Z(X, Y)U\}. \end{aligned}$$

Equation (3.18) then gives

$$\left(1 + \frac{r}{n(n-1)}\right) \left(Z(X, Y)U - \left(1 + \frac{r}{n(n-1)}\right) (g(Y, U)X - g(X, U)Y)\right) = 0.$$

Therefore either the scalar curvature $r = n(1 - n)$ or

$$Z(X, Y)U - \left(1 - \frac{r}{n(n-1)}\right) (g(Y, U)X - g(X, U)Y) = 0$$

which in view of (2.16) gives

$$R(X, Y)U = g(U, X)Y - g(U, Y)X.$$

The above equation implies that M is of constant curvature -1 and consequently it is locally isometric to the Hyperbolic space $H^n(-1)$.

Conversely, if M has scalar curvature $r = n(1 - n)$ then from (3.19) it follows that $Z(\xi, X) = 0$. Similarly, in the second case, since M is of constant curvature $r = n(1 - n)$, therefore we again get $Z(\xi, X) = 0$. \square

Using the fact that $Z(\xi, X) \cdot R$ denotes $Z(\xi, X)$ acting on R as a derivation, we have the following Theorem as a corollary of Theorem 3.1.

Theorem 3.2 *An n -dimensional P -Sasakian manifold M satisfies*

$$Z(\xi, X) \cdot R = 0$$

if and only if either M is locally isometric to the Hyperbolic space $H^n(-1)$ or M has constant scalar curvature $r = n(1 - n)$.

Proposition 3.3 *Let (M, g) be an n -dimensional Riemannian manifold. Then $R \cdot Z = R \cdot R$.*

Proof. Let $X, Y, U, V, W \in TM$. Then

$$\begin{aligned} (R(X, Y) \cdot Z)(U, V, W) &= R(X, Y)Z(U, V)W - Z(R(X, Y)U, V)W \\ &\quad - Z(U, R(X, Y)V)W - Z(U, V)R(X, Y)W. \end{aligned}$$

So from (2.16) and the symmetry properties of the curvature tensor R we have

$$\begin{aligned} (R(X, Y) \cdot Z)(U, V, W) &= R(X, Y)R(U, V)W - R(R(X, Y)U, V)W \\ &\quad - R(U, R(X, Y)V)W - R(U, V)R(X, Y)W \\ &= (R(X, Y) \cdot R)(U, V, W), \end{aligned}$$

which proves the proposition. \square

Now, in view of Theorem 2.1 of [2] and Proposition 3.3 we have the following theorem:

Theorem 3.4 *An n -dimensional P -Sasakian manifold M satisfies*

$$R(\xi, X) \cdot Z = 0$$

if and only if M is locally isometric to the Hyperbolic space $H^n(-1)$.

Next, we prove the following

Theorem 3.5 *An n -dimensional P -Sasakian manifold M satisfies*

$$Z(\xi, X) \cdot S = 0$$

if and only if either M has scalar curvature $r = n(1 - n)$ or M is an Einstein manifold with the scalar curvature $r = n(1 - n)$.

Proof. The condition $Z(\xi, X) \cdot S = 0$ implies that

$$S(Z(\xi, X)Y, \xi) + S(Y, Z(\xi, X)\xi) = 0,$$

which in view of (3.19) gives

$$0 = \left(1 + \frac{r}{n(n-1)}\right) (-g(X, Y)S(\xi, \xi) + \eta(Y)S(X, \xi) - \eta(X)S(Y, \xi) + S(X, Y)).$$

So by the use of (2.10) we have

$$\left(1 + \frac{r}{n(n-1)}\right) (S - (1 - n)g) = 0.$$

Therefore either the scalar curvature r of M is $r = n(1 - n)$ which is of constant or $S = (1 - n)g$ which implies that M is an Einstein manifold with the scalar curvature $r = n(1 - n)$. The converse statement is trivial. \square

Theorem 3.6 *An n -dimensional P -Sasakian manifold M satisfies*

$$Z(\xi, X) \cdot C = 0$$

if and only if either M has scalar curvature $r = n(1 - n)$ or M is conformally flat, in which case M is a SP -Sasakian manifold.

Proof. $Z(\xi, U) \cdot C = 0$ implies that

$$0 = [Z(\xi, U), C(X, Y)]W - C(Z(\xi, U)X, Y)W - C(X, Z(\xi, U)Y)W,$$

which in view of (3.19) we have

$$\begin{aligned} 0 &= \left(1 + \frac{r}{n(n-1)}\right)[\eta(C(X, Y)W)U - C(X, Y, W, U)\xi - \eta(X)C(U, Y)W \\ &+ g(U, X)C(\xi, Y)W - \eta(Y)C(X, U)W + g(U, Y)C(X, \xi)W \\ &- \eta(W)C(X, Y)U + g(U, W)C(X, Y)\xi]. \end{aligned}$$

So either the scalar curvature of M is $r = n(1 - n)$ or the equation

$$\begin{aligned} 0 &= \eta(C(X, Y)W)U - C(X, Y, W, U)\xi - \eta(X)C(U, Y)W \\ &+ g(U, X)C(\xi, Y)W - \eta(Y)C(X, U)W + g(U, Y)C(X, \xi)W \\ &- \eta(W)C(X, Y)U + g(U, W)C(X, Y)\xi \end{aligned}$$

holds on M . Taking the inner product of the last equation with ξ we get

$$\begin{aligned} 0 &= \eta(C(X, Y)W)\eta(U) - C(X, Y, W, U) \\ &- \eta(X)\eta(C(U, Y)W) + g(U, X)\eta(C(\xi, Y)W) - \eta(Y)\eta(C(X, U)W) \\ &+ g(U, Y)\eta(C(X, \xi)W) - \eta(W)\eta(C(X, Y)U). \end{aligned} \tag{3.20}$$

Hence using (2.10), (2.12) and (2.17) the equation (3.20) turns the form

$$\begin{aligned} 0 &= g(U, Y)g(X, W) - g(U, X)g(Y, W) \\ &+ \frac{1-n}{n-2}\{-g(Y, W)g(X, U) + g(X, W)g(U, Y) \\ &+ g(X, U)\eta(Y)\eta(W) - g(U, Y)\eta(X)\eta(W)\} \\ &+ \frac{1}{n-2}\{S(Y, U)\eta(X)\eta(W) - S(X, U)\eta(Y)\eta(W) \\ &+ g(Y, W)S(X, U) - g(X, W)S(Y, U)\} - R(X, Y, W, U). \end{aligned} \tag{3.21}$$

Hence by a suitable contraction of (3.21) we have

$$S(Y, W) = \left(1 + \frac{r}{n-1}\right)g(Y, W) + \left(-n + \frac{r}{1-n}\right)\eta(Y)\eta(W), \tag{3.22}$$

which implies that M is an η -Einstein manifold. So using (3.22) in (3.20) we obtain $C = 0$ on M . Thus using the fact from [1] that a conformally flat P -Sasakian manifold is an SP -Sasakian, M becomes an SP -Sasakian manifold. The converse statement is trivial. \square

4. An application

A Riemannian manifold is said to be *concircularly symmetric* if the concircular curvature tensor Z is parallel, that is, $\nabla Z = 0$. Now, we prove the following theorem.

Theorem 4.1 *In a P -Sasakian manifold M the following conditions are equivalent:*

- (a) M is locally symmetric,
- (b) M is concircularly symmetric,
- (c) M is locally isometric to the Hyperbolic space $H^n(-1)$.

Proof. It is obvious that the condition $\nabla T = 0$, $T \in \{R, Z\}$, implies the condition $R \cdot T = 0$. From Theorem 2.1 of [2] and Theorem 3.4, it follows that M satisfies the condition $R(\xi, X) \cdot T = 0$, $T \in \{R, Z\}$ if and only if M is locally isometric to the Hyperbolic space $H^n(-1)$. \square

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